

Kernelization Complexity of Possible Winner and Coalitional Manipulation Problems in Voting

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ABSTRACT

In the POSSIBLE WINNER problem in computational social choice theory, we are given a set of partial preferences and the question is whether a distinguished candidate could be made winner by extending the partial preferences to linear preferences. Previous work has provided, for many common voting rules, fixed parameter tractable algorithms for the POSSIBLE WINNER problem, with number of candidates as the parameter. However, the corresponding kernelization question is still open and in fact, has been mentioned as a key research challenge [10]. In this paper, we settle this open question for many common voting rules.

We show that the POSSIBLE WINNER problem for maximin, Copeland, Bucklin, ranked pairs, and a class of scoring rules that include the Borda voting rule do not admit a polynomial kernel with the number of candidates as the parameter. We show however that the COALITIONAL MANIPULATION problem which is an important special case of the POSSIBLE WINNER problem does admit a polynomial kernel for maximin, Copeland, ranked pairs, and a class of scoring rules that includes the Borda voting rule, when the number of manipulators is polynomial in the number of candidates. A significant conclusion of our work is that the POSSIBLE WINNER problem is harder than the COALITIONAL MANIPULATION problem since the COALITIONAL MANIPULATION problem admits a polynomial kernel whereas the POSSIBLE WINNER problem does not admit a polynomial kernel.

Categories and Subject Descriptors

F.2 [Theory of Computation]: Analysis of Algorithms and Problem Complexity;

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General Terms

Algorithms, Theory

Keywords

Computational social choice; possible winner; voting; kernelization; parameterized complexity

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1. INTRODUCTION

In many real life situations including multiagent systems, agents often need to aggregate their preferences and agree upon a common decision (candidate). Voting is an immediate natural tool in these situations. Common and classical applications of voting rules in artificial intelligence include collaborative filtering [31], planning among multiple automated agents [19], etc.

Usually, in a voting setting, it is assumed that the votes are complete orders over the candidates. However, due to many reasons, for example, lack of knowledge of voters about some candidates, a voter may be indifferent between some pairs of candidates. Hence, it is both natural and important to consider scenarios where votes are partial orders over the candidates. When votes are only partial orders over the candidates, the winner cannot be determined with certainty since it depends on how these partial orders are extended to linear orders. This leads to a natural computational problem called the POSSIBLE WINNER [25] problem: given a set of partial votes P and a distinguished candidate c , is there a way to extend the partial votes to linear ones to make c win? The POSSIBLE WINNER problem has been studied extensively in the literature [2,5,6,8,14,22,26,27,32,33,35] following its definition in [25]. The POSSIBLE WINNER problem is known to be in NPC for many common voting rules, for example, scoring rules, maximin, Copeland, Bucklin, and ranked pairs etc. [35]. Walsh [33] showed, for a constant number of candidates, that the POSSIBLE WINNER problem can be solved in polynomial time for all the voting rules mentioned above. An important special case of the POSSIBLE WINNER problem is the COALITIONAL MANIPULATION problem [1] where only two kinds of partial votes are allowed - complete preference and empty preference. The set of empty votes is called the manipulators' vote and is denoted by M . The COALITIONAL MANIPULATION problem is in NPC for maximin, Copeland, and ranked pairs voting rules even when $|M| \geq 2$ [20,21,36]. The COALITIONAL MANIPULATION problem is in P for the Bucklin voting rule [36]. We refer to [33,35,36] for detailed overviews.

1.1 Our Methodology

Preprocessing, as a strategy for coping with hard problems, is universally applied in practice. The main goal here is *instance compression* - the objective is to output a smaller instance while maintaining equivalence. In the classical setting, NP-hard problems are unlikely to have efficient compression algorithms (since repeated application would lead to an efficient solution for the entire problem, which is unexpected). However, the breakthrough notion of *kernelization* in parameterized complexity provides a mathematical framework for analyzing the quality of preprocessing strategies. In parameterized complexity, each problem instance (x, k) comes

with a parameter k . The parameterized problem is said to admit a *kernel* if there is a polynomial time algorithm (where the degree of polynomial is independent of k), called a *kernelization algorithm*, that reduces the input instance to an instance with size bounded by a function of k , while preserving the answer. This has turned out to be an important and widely applied notion in theory, and has also proven very successful in practice [28, 34]. Quantitatively, running a kernelization algorithm before solving it using an algorithm that runs in time $f(|x|)$ brings down the running time to $f(k) + p(|x|)$, where $|x|$ is the size of the input instance and the running time of the kernelization algorithm is $p(|x|)$.

A problem with parameter k is called *fixed parameter tractable* (FPT) if it is solvable in time $f(k) \cdot p(|x|)$, where f is an arbitrary function of k and p is a polynomial in the input size $|x|$. The existence of a fixed parameter tractable algorithm implies existence of a kernel for that problem. However, the size of the kernel need not be polynomial in the parameter. A polynomial kernel is said to exist if there is a kernelization algorithm that can output an equivalent problem instance of size polynomial in the parameter. We refer to [18, 30] for an excellent overview on fixed parameter algorithms and kernelization.

1.2 Contributions

Discovering kernelization algorithms is currently an active and interesting area of research in computational social choice theory [3–5, 7, 11, 12, 17, 24]. Betzler et al. [8] showed that the POSSIBLE WINNER problem has a kernelization algorithm when parameterized by the total number of candidates for scoring rules, maximin, Copeland, Bucklin, and ranked pairs voting rules. A natural and practical follow-up question is whether the problem admits a polynomial kernel when parameterized by the number of candidates. This question has been open ever since the work of Betzler et al. and in fact, has been mentioned as a key research challenge in parameterized algorithms for computational social choice theory [10]. Betzler et al. showed non-existence of polynomial kernel for the POSSIBLE WINNER problem for the k -approval voting rule when parameterized by (t, k) , where t is the number of partial votes [3]. The NPC reductions for the POSSIBLE WINNER problem for scoring rules, maximin, Copeland, Bucklin, and ranked pairs voting rules given by Xia et al. [36] are from the EXACT 3 SET-COVER problem. Their results do not throw any light on the existence of a polynomial kernel since EXACT 3 SET-COVER has a trivial $O(m^3)$ kernel where m is the size of the universe. In our work in this paper, we show that there is no polynomial kernel for the POSSIBLE WINNER problem for maximin, Copeland, Bucklin, ranked pairs, and a class of scoring rules that include the Borda voting rule, when parameterized by the total number of candidates unless $\text{CoNP} \subseteq \text{NP/Poly}$. These hardness results are shown by a parameter-preserving many-to-one reduction from the SMALL UNIVERSE SET COVER problem for which there does not exist any polynomial kernel parameterized by universe size unless $\text{CoNP} \subseteq \text{NP/Poly}$ [16].

On the other hand, we show that the COALITIONAL MANIPULATION problem admits a polynomial kernel for maximin, Copeland, ranked pairs, and a class of scoring rules that includes the Borda voting rule when we have $O(\text{poly}(m))$ number of manipulators – specifically, we exhibit an $O(m^2|M|)$ kernel for maximin and Copeland, and an $O(m^4|M|)$ kernel for the ranked pairs voting rule, where m is the number of candidates and M is the set of manipulators. The COALITIONAL MANIPULATION problem for the Bucklin voting rule is in P [36] and thus the kernelization question does not arise.

A significant conclusion of our work is that, although the POSSIBLE WINNER and COALITIONAL MANIPULATION problems are both NPC, the POSSIBLE WINNER problem is harder than the COALI-

TIONAL MANIPULATION problem since the COALITIONAL MANIPULATION problem admits a polynomial kernel whereas the POSSIBLE WINNER problem does not admit a polynomial kernel.

The rest of the paper is organized as follows. We first establish the setup and general notions. Next, we discuss non-existence of polynomial kernels for the POSSIBLE WINNER problem followed by existence of polynomial kernels for the COALITIONAL MANIPULATION problem.

2. PRELIMINARIES

Let $\mathcal{V} = \{v_1, \dots, v_n\}$ be the set of all *voters* and $\mathcal{C} = \{c_1, \dots, c_m\}$ the set of all *candidates*. From, here on, n is the number of voters and m is the number of candidates unless mentioned otherwise. Each voter v_i 's vote is a *preference* \succ_i over the candidates which is a linear order over \mathcal{C} . For example, for two candidates a and b , $a \succ_i b$ means that the voter v_i prefers a to b . We will use $a \succ_i b$ to denote the fact that $a \succ_i b$, $a \neq b$. We denote the set of all linear orders over \mathcal{C} by $\mathcal{L}(\mathcal{C})$. The set of all preference profiles $(\succ_1, \dots, \succ_n)$ of the n voters is denoted by $\mathcal{L}(\mathcal{C})^n$. We use $x \% y$ to denote the modulus operation $x \bmod y$ (for example, $5 \% 2$ is the same as 1). We denote the set $\{1, 2, \dots\}$ by \mathbb{N}^+ and the set $\{1, \dots, k\}$ by $[k]$. Let \uplus denote the disjoint union of sets. A map $r : \uplus_{n, \mathcal{C}} \mathcal{L}(\mathcal{C})^n \rightarrow 2^{\mathcal{C}} \setminus \{\emptyset\}$ is called a *voting rule*. For a voting rule r and a preference profile \succ , we say a candidate x wins uniquely if $r(\succ) = \{x\}$. In this paper, unless mentioned otherwise, winning means winning uniquely. A more general setting is an *election* where the votes are only *partial orders* over candidates. A *partial order* is a relation that is *reflexive*, *antisymmetric*, and *transitive*. A partial vote can be extended to possibly more than one linear votes depending on how we fix the order for the unspecified pairs of candidates. For example, in an election with the set of candidates $\mathcal{C} = \{a, b, c\}$, a valid partial vote can be $a \succ b$. This partial vote can be extended to three linear votes namely, $a \succ b \succ c$, $a \succ c \succ b$, $c \succ a \succ b$. However, the voting rules always take as input a set of votes that are complete orders over the candidates. Some examples of common voting rules are as follows.

Positional scoring rules. Given an m -dimensional vector $\vec{\alpha} = (\alpha_1, \alpha_2, \dots, \alpha_m) \in \mathbb{R}^m$ with $\alpha_1 \geq \alpha_2 \geq \dots \geq \alpha_m$, we can naturally define a voting rule - a candidate gets score α_i from a vote if it is placed at the i^{th} position, and the score of a candidate is the sum of the scores it receives from all the votes. The winners are the candidates with maximum score. Scoring rules remain unchanged if we multiply every α_i by any constant $\lambda > 0$ and/or add any constant μ . Hence, we assume without loss of generality that for any score vector $\vec{\alpha}$, there exists a j such that $\alpha_j - \alpha_{j+1} = 1$ and $\alpha_k = 0$ for all $k > j$. We call such an $\vec{\alpha}$ a normalized score vector. A scoring rule is called a strict scoring rule if $\alpha_1 > \alpha_2 > \dots > \alpha_m$. For $\alpha = (m-1, m-2, \dots, 1, 0)$, we get the *Borda* voting rule. With $\alpha_i = 1 \forall i \leq k$ and 0 else, the voting rule we get is known as *k-approval*. *Plurality* is 1-approval and *veto* is $(m-1)$ -approval.

Bucklin. A candidate x 's Bucklin score is the minimum number l such that more than half of the voters rank x in their top l positions. The winners are the candidates with lowest Bucklin score.

Given an election E , we can construct a weighted graph G_E called *weighted majority graph* from E . The set of vertices in G_E is the set of candidates in E . For any two candidates x and y , the weight on the edge (x, y) is $D_E(x, y) = N_E(x, y) - N_E(y, x)$, where $N_E(x, y)$ ($N_E(y, x)$) is the number of voters who prefer x to y (y to x). The following voting rules use weighted majority graph to select winner.

Maximin. The maximin score of a candidate x is $\min_{y \neq x} D(x, y)$. The winners are the candidates with maximum maximin score.

Copeland. The Copeland score of a candidate x is the number of candidates $y \neq x$ such that $D(x, y) > 0$. The winners are the candidates with maximum Copeland score.

Ranked pairs. We pick the pair $(c_i, c_j) \in \mathcal{C} \times \mathcal{C}$ such that $D(c_i, c_j)$ is maximum. We fix the ordering between c_i and c_j to be $c_i \succ c_j$ unless it contradicts previously fixed orders. We continue this process until all pairwise elections are considered. At this point, we have a complete order over the candidates. Now, the top candidate is chosen as the winner.

We use the parallel-universes tie breaking [13, 15] to define the winning candidate for the ranked pairs voting rule. In this setting, a candidate c is a winner if and only if there exists a way to break ties in all of the steps such that c is the winner. We say that a candidate is the unique winner of a ranked pairs election if the candidate is the sole winner in all possible tie breakings in all the steps.

We now briefly describe the framework in which we analyze the computational complexity of the POSSIBLE WINNER problem.

Parameterized Complexity. A parameterized problem Π is a subset of $\Gamma^* \times \mathbb{N}$, where Γ is a finite alphabet. An instance of a parameterized problem is a tuple (x, k) , where k is the parameter. A *kernelization* algorithm is a set of preprocessing rules that runs in polynomial time and reduces the instance size with a guarantee on the output instance size. This notion is formalized below.

Definition 1. [Kernelization] [23, 30] *A kernelization algorithm for a parameterized problem $\Pi \subseteq \Gamma^* \times \mathbb{N}$ is an algorithm that, given $(x, k) \in \Gamma^* \times \mathbb{N}$, outputs, in time polynomial in $|x| + k$, a pair $(x', k') \in \Gamma^* \times \mathbb{N}$ such that (a) $(x, k) \in \Pi$ if and only if $(x', k') \in \Pi$ and (b) $|x'|, k' \leq g(k)$, where g is some computable function. The output instance x' is called the kernel, and the function g is referred to as the size of the kernel. If $g(k) = k^{O(1)}$ then we say that Π admits a polynomial kernel.*

For many parameterized problems, it is well established that the existence of a polynomial kernel would imply the collapse of the polynomial hierarchy to the third level (or more precisely, $\text{CoNP} \subseteq \text{NP}/\text{Poly}$). Therefore, it is considered unlikely that these problems would admit polynomial-sized kernels. For showing kernel lower bounds, we simply establish reductions from these problems.

Definition 2. [Polynomial Parameter Transformation] [9] *Let Γ_1 and Γ_2 be parameterized problems. We say that Γ_1 is polynomial time and parameter reducible to Γ_2 , written $\Gamma_1 \leq_{\text{Ptp}} \Gamma_2$, if there exists a polynomial time computable function $f : \Sigma^* \times \mathbb{N} \rightarrow \Sigma^* \times \mathbb{N}$, and a polynomial $p : \mathbb{N} \rightarrow \mathbb{N}$, and for all $x \in \Sigma^*$ and $k \in \mathbb{N}$, if $f((x, k)) = (x', k')$, then $(x, k) \in \Gamma_1$ if and only if $(x', k') \in \Gamma_2$, and $k' \leq p(k)$. We call f a polynomial parameter transformation (or a PPT) from Γ_1 to Γ_2 .*

This notion of a reduction is useful in showing kernel lower bounds because of the following theorem.

Theorem 1. [9, Theorem 3] *Let P and Q be parameterized problems whose derived classical problems are P^c, Q^c , respectively. Let P^c be NPC, and $Q^c \in \text{NP}$. Suppose there exists a PPT from P to Q . Then, if Q has a polynomial kernel, then P also has a polynomial kernel.*

3. HARDNESS OF KERNELIZATION FOR POSSIBLE WINNER PROBLEM

In this section, we show non-existence of polynomial kernels for the POSSIBLE WINNER problem for maximin, Copeland, Bucklin,

ranked Pairs, and a class of scoring rules that includes the Borda voting rule. We do this by demonstrating polynomial parameter transformations from the SMALL UNIVERSE SET COVER problem, which is the classic SET COVER problem, but now parameterized by the size of the universe and the budget.

SMALL UNIVERSE SET COVER	Parameter: $m + k$
Input: A set $\mathcal{U} = \{u_1, \dots, u_m\}$ and a family $\mathcal{F} = \{S_1, \dots, S_t\}$.	
Question: Is there a subfamily $\mathcal{H} \subseteq \mathcal{F}$ of size at most k such that every element of the universe belongs to at least one $H \in \mathcal{H}$?	

It is well-known [16] that RED-BLUE DOMINATING SET parameterized by k and the number of non-terminals does not admit a polynomial kernel unless $\text{CoNP} \subseteq \text{NP}/\text{Poly}$. It follows, by the duality between dominating set and set cover, that SET COVER when parameterized by the solution size and the size of the universe (in other words, the SMALL UNIVERSE SET COVER problem defined above) does not admit a polynomial kernel unless $\text{CoNP} \subseteq \text{NP}/\text{Poly}$.

We now consider the POSSIBLE WINNER problem parameterized by the number of candidates for maximin, Copeland, Bucklin, ranked pairs, and a class of scoring rules that includes the Borda rule, and establish that they do not admit a polynomial kernel unless $\text{CoNP} \subseteq \text{NP}/\text{Poly}$, by polynomial parameter transformations from SMALL UNIVERSE SET COVER.

3.1 Scoring Rules

First, we prove hardness of kernelization for the POSSIBLE WINNER problem for a large class of scoring rules that includes the Borda rule. For that, we use the following lemma which has been used before [2].

Lemma 1. *Let $\mathcal{C} = \{c_1, \dots, c_m\} \uplus D$, ($|D| > 0$) be a set of candidates, and $\vec{\alpha}$ a normalized score vector of length $|\mathcal{C}|$. Then, for any given $\mathbf{X} = (X_1, \dots, X_m) \in \mathbb{Z}^m$, there exists $\lambda \in \mathbb{R}$ and a voting profile such that the $\vec{\alpha}$ -score of c_i is $\lambda + X_i$ for all $1 \leq i \leq m$, and the score of candidates $d \in D$ is less than λ . Moreover, the number of votes is $O(\text{poly}(|\mathcal{C}| \cdot \sum_{i=1}^m |X_i|))$.*

Theorem 2. *The POSSIBLE WINNER problem for any strict scoring rule, when parameterized by the number of candidates, does not admit a polynomial kernel unless $\text{CoNP} \subseteq \text{NP}/\text{Poly}$.*

PROOF. Let $(\mathcal{U}, \mathcal{F}, k)$ be an instance of SMALL UNIVERSE SET COVER, where $\mathcal{U} = \{u_1, \dots, u_m\}$ and $\mathcal{F} = \{S_1, \dots, S_t\}$. We use T_i to denote $\mathcal{U} \setminus S_i$. We let $(\alpha_1, \alpha_2, \dots, \alpha_t)$ denote the score vector of length t , and let δ_i denote the difference $(\alpha_i - \alpha_{i+1})$. Note that for a strict scoring rule, all the δ_i 's will be strictly positive. We now construct an instance (\mathcal{C}, V, c) of POSSIBLE WINNER as follows.

Candidates. $\mathcal{C} = \mathcal{U} \uplus \mathcal{V} \uplus \{w, c, d\}$, where $\mathcal{V} := \{v_1, \dots, v_m\}$.

Partial Votes, P . The first part of the voting profile comprises t partial votes, and will be denoted by P_1 . Let V_j denote the set $\{v_1, \dots, v_j\}$. For each $1 \leq i \leq t$, we first consider a profile built on a total order η_i :

$$\eta_i := d \succ S_i \succ V_j \succ w \succ \dots, \text{ where } j = m - |S_i|.$$

Now, we obtain a partial order λ_i based on η_i as follows:

$$\lambda_i := \eta_i \setminus (\{w\} \times (\{d\} \uplus S_i \uplus V_j))$$

Let P'_i be the set of votes $\{\eta_i \mid 1 \leq i \leq t\}$. We will now add more votes, which we denote by P_2 , such that $s(c) = s(u_i)$, $s(d) - s(c) = (k - 1)\delta_1$, $s(c) - s(w) = k(\delta_2 + \delta_3 + \dots + \delta_{m+1}) + \delta_1$, $s(c) > s(v_i) + 1$, for all $1 \leq i \leq t$ where $s(\cdot)$ is the scores of the candidates from the combined voting profile $P'_1 \uplus P_2$. From the

proof of Lemma 1, we can see that such votes can always be constructed. In particular, also note that the voting profile P_2 consists of complete votes. Note that the number of candidates is $2m + 3$, which is polynomial in the size of the universe, as desired. We now claim that the candidate c is a possible winner for the voting profile $P_1 \uplus P_2$ with respect to the strict scoring rule if, and only if, $(\mathcal{U}, \mathcal{F})$ is a YES-instance of Set Cover.

In the forward direction, suppose, without loss of generality, that S_1, \dots, S_k form a set cover. Then we propose the following extension for the partial votes $\lambda_1, \dots, \lambda_k$:

$$w > d > S_i > V_j > \dots,$$

and the following extension for the partial votes $\lambda_{k+1}, \dots, \lambda_t$:

$$d > S_i > V_j > w > \dots$$

For $1 \leq i \leq k$, the position of d in the extension of λ_i proposed above is δ_1 lower than its original position in η_i . Therefore, the final score of d is lower than the score of c . Similarly, the scores of all the u_i 's decrease by at least $\min_{i=2}^m \{\delta_i\}$, which is strictly positive, since the S_i 's together form a set cover, and the scoring rule is strict. Finally, the score of w increase by at most $k(\delta_2 + \delta_3 + \dots + \delta_{m+1})$, since there are at most k votes where the position of w in the extension of λ_i improved from its original position in η_i . Therefore, the score of c is greater than any other candidate, implying that c is a possible winner.

For the reverse direction, notice that there must be at least k extensions where d is in the second position, since the score of d is $(k-1)\delta_1$ more than the score of c . In these extensions, observe that w will be at the first position. On the other hand, placing w in the first position causes its score to increase by $(\delta_2 + \delta_3 + \dots + \delta_{m+1})$, therefore, if w is in first position in ℓ extensions, its score increases by $\ell(\delta_2 + \delta_3 + \dots + \delta_{m+1})$. Since the score difference between w and c is only $k(\delta_2 + \delta_3 + \dots + \delta_{m+1}) + 1$, we can afford to have w in the first position in *at most* k votes. Therefore, apart from the extensions where d is in the second position, in all remaining extensions, w appears after V_j , and therefore the candidates from S_i continue to be in their original positions. We now claim that the sets corresponding to the k votes where d is on top form a set cover. Indeed, if not, suppose the element u_i is not covered. It is easily checked that the score of such a u_i remains unchanged in this extension, and therefore its score is equal to c , contradicting our assumption that we started with an extension for which c was a winner. \square

The proof of Theorem 2 can be generalized to a wider class of scoring rules as stated in the following corollary.

Corollary 1. *Let r be a positional scoring rule such that there exists a polynomial function $f : \mathbb{N} \rightarrow \mathbb{N}$, such that for every $m \in \mathbb{N}$, there exists an index l in the $f(m)$ length score vector $\vec{\alpha}$ satisfying following,*

$$\alpha_i - \alpha_{i+1} > 0, \forall l \leq i \leq l + m$$

Then, the POSSIBLE WINNER problem for r , when parameterized by the number of candidates, does not admit a polynomial kernel unless $\text{CoNP} \subseteq \text{NP/Poly}$.

3.2 Maximin Voting Rule

We will need the following lemma in subsequent proofs. The lemma has been used before [29, 35].

Lemma 2. *For any function $f : \mathcal{C} \times \mathcal{C} \rightarrow \mathbb{Z}$, such that*

1. $\forall a, b \in \mathcal{C}, f(a, b) = -f(b, a)$.
2. *either* $\forall a, b \in \mathcal{C}, f(a, b)$ *is even or* $\forall a, b \in \mathcal{C}, f(a, b)$ *is odd.*

there exists a n voters' profile such that for all $a, b \in \mathcal{C}$, a defeats b with a margin of $f(a, b)$. Moreover,

$$n = O\left(\sum_{\{a,b\} \in \mathcal{C} \times \mathcal{C}} |f(a,b)|\right)$$

We now describe the reduction for the POSSIBLE WINNER parameterized by the number of candidates, for the maximin voting rule.

Theorem 3. *The POSSIBLE WINNER problem for maximin voting rule, when parameterized by the number of candidates, does not admit a polynomial kernel unless $\text{CoNP} \subseteq \text{NP/Poly}$.*

PROOF. Let $(\mathcal{U}, \mathcal{F}, k)$ be an instance of SMALL UNIVERSE SET COVER, where $\mathcal{U} = \{u_1, \dots, u_m\}$ and $\mathcal{F} = \{S_1, \dots, S_t\}$. We use T_i to denote $\mathcal{U} \setminus S_i$. We now construct an instance (\mathcal{C}, V, c) of the POSSIBLE WINNER as follows.

Candidates. $C := \mathcal{U} \uplus W \uplus \{c, d, x\} \uplus L$. Where $W := \{w_1, w_2, \dots, w_m, w_x\}$, $L := \{l_1, l_2, l_3\}$.

Partial Votes, P . The first part of the voting profile comprises t partial votes, and will be denoted by P . For each $1 \leq i \leq t$, we first consider a profile built on a total order η_i . We denote the order $w_1 \succ \dots \succ w_m \succ w_x$ by \vec{W} . From this point onwards, whenever we place a set of candidates in some position of a partial order, we mean that the candidates in the set can be ordered arbitrarily. For example, the candidates in S_i can be ordered arbitrarily among themselves in the total order η_i below.

$$\eta_i := L \succ \vec{W} \succ x \succ S_i \succ d \succ c \succ T_i$$

Now, we obtain a partial order λ_i based on η_i as follows:

$$\lambda_i := \eta_i \setminus (W \times (\{c, d, x\} \uplus \mathcal{U}))$$

The profile P consists of $\{\lambda_i \mid 1 \leq i \leq t\}$.

Complete Votes, Q . We now describe the remaining votes in the profile, which are linear orders designed to achieve specific pairwise difference scores among the candidates. This profile, denoted by Q , is defined according to Lemma 2 to contain votes such that $D(c, w_1) = -2k, D(c, l_1) = -t, D(d, w_1) = -2k - 2, D(x, w_x) = -2k - 2, D(w_i, u_i) = -2t \forall 1 \leq i \leq m, D(a_i, l_1) = D(w_x, l_1) = -4t, D(l_1, l_2) = D(l_2, l_3) = D(l_3, l_1) = -4t, D(l, r) \leq 1$ for all other pairs $(l, r) \in \mathcal{C} \times \mathcal{C}$, are the pairwise score differences of $P \uplus Q$. We note that for all $c, c' \in \mathcal{C}$, the difference $|D(c, c') - D_P(c, c')|$ is always even, as long as t is even and the number of sets in \mathcal{F} that contain an element $u \in \mathcal{U}$ is always even. Note that the latter can always be ensured without loss of generality: indeed, if $u \in \mathcal{U}$ occurs in an odd number of sets, then we can always add the set $\{u\}$ if it is missing and remove it if it is present, flipping the parity in the process. In case $\{u\}$ is the only set containing the element u , then we remove the set from both \mathcal{F} and \mathcal{U} and decrease k by one. The number of sets t can be assumed to be even by adding a dummy element and a dummy pair of sets that contains the said element. Thus, the constructed instance of POSSIBLE WINNER is (\mathcal{C}, V, c) , where $V := P \uplus Q$. We now turn to the proof of correctness.

In the forward direction, let $\mathcal{H} \subseteq \mathcal{F}$ be a set cover of size at most k . Without loss of generality, let $|\mathcal{H}| = k$ (since a smaller set cover can always be extended artificially) and let $\mathcal{H} = \{S_1, \dots, S_k\}$ (by renaming).

$$\lambda_i^* := L \succ x \succ S_i \succ d \succ c \succ \vec{W} \succ T_i, \text{ if } i \leq k$$

$$\lambda_i^* := L \succ \vec{W} \succ x \succ S_i \succ d \succ c \succ T_i, \text{ if } i > k$$

Clearly λ_i^* extends λ_i for all $i \in 1 \leq i \leq k$. Let V^* denote the extended profile consisting of the votes $\{\lambda_i^* \mid 1 \leq i \leq k\} \uplus Q$.

We now claim that c is the unique winner with respect to maximin voting rule in V^* .

Since there are k votes in V^* where c is preferred over w_1 and $(t - k)$ votes where w_1 is preferred to c , we have:

$$\begin{aligned} D_{V^*}(c, w_1) &= D_V(c, w_1) + k - (t - k) \\ &= -2k + k - (t - k) = -t \end{aligned}$$

It is easy to check that maximin score of c is $-t$. Also, it is straightforward to verify that the maximin score of w_i is less than $-t$ for every $i \in [m]$, the maximin score of d and x is at most $-t - 2$ and the maximin score of every other candidate is at most $-4t$. Therefore, c is the unique winner for the profile V^* .

We now turn to the reverse direction. Let P^* be an extension of P such that $V^* := P^* \uplus Q$ admits c as a unique winner. We first argue that P^* must admit a certain structure, which will lead us to an almost self-evident set cover for \mathcal{U} .

Let us denote by P_C^* the set of votes in P^* which are consistent with $c \succ w_1$, and let P_W^* be the set of votes in P^* which are consistent with $w_1 \succ c$. We first argue that P_C^* has at most k votes.

Claim 1. *Let P_C^* be as defined above. Then, $|P_C^*| \leq k$.*

PROOF. Suppose, for the sake of contradiction, that more than k extensions are consistent with $c \succ w_1$. Then we have:

$$\begin{aligned} D_{V^*}(c, w_1) &\geq D_V(c, w_1) + k + 1 - (t - k - 1) \\ &= -2k + 2k - t + 2 = -t + 2 \end{aligned}$$

Since $D_{V^*}(c, l_1) = -t$, the maximin score of c is $-t$. On the other hand, we also have that the maximin score of d is given by $D_{V^*}(d, w_1)$, which is now at least $(-t)$:

$$\begin{aligned} D_{V^*}(d, w_1) &\geq D_V(d, w_1) + k + 1 - (t - k - 1) \\ &= -2k - 2 + 2k - t + 2 = -t \end{aligned}$$

Therefore, c is no longer the unique winner in V^* with respect to the maximin voting rule, which is the desired contradiction. \square

Next, we propose that a vote that is consistent with $w_1 \succ c$ must be consistent with $w_x \succ x$.

Claim 2. *Let P_W^* be as defined above. Then, any vote in P_W^* must respect $w_x \succ x$.*

PROOF. Suppose there are r votes in P_C^* , and suppose that in at least one vote in P_W^* where $x \succ w_x$. Notice that any vote in P_C^* is consistent with $x \succ w_x$. Now we have:

$$\begin{aligned} D_{V^*}(c, w_1) &= D_V(c, w_1) + r - (t - r) \\ &= -2k + 2r - t \\ &= -t - 2(k - r) \end{aligned}$$

And further:

$$\begin{aligned} D_{V^*}(x, w_x) &\geq D_V(x, w_x) + (r + 1) - (t - r - 1) \\ &= -2k - 2 + 2r - t + 2 \\ &= -t - 2(k - r) \end{aligned}$$

It is easy to check that the maximin score of c in V^* is at most $-t - 2(k - r)$, witnessed by $D_{V^*}(c, w_1)$, and the maximin score of x is at least $-t - 2(k - r)$, witnessed by $D_{V^*}(x, w_x)$. Therefore, c is no longer the unique winner in V^* with respect to the maximin voting rule, and we have a contradiction. \square

We are now ready to describe a set cover of size at most k for \mathcal{U} based on V^* . Define $J \subseteq [t]$ as being the set of all indices i for which the extension of λ_i in V^* belongs to P_C^* . Consider:

$$\mathcal{H} := \{S_i \mid i \in J\}.$$

The set \mathcal{H} is our proposed set cover. Clearly, $|\mathcal{H}| \leq k$. It remains to be shown that \mathcal{H} is a set cover.

Assume, for the sake of contradiction, that there is an element $u_i \in \mathcal{U}$ that is not covered by \mathcal{H} . This means that for all $i \in J$, $u_i \in T_i$, and in the corresponding extensions of λ_i in V^* , implying that $w_i \succ u_i$. Further, for all $i \notin J$, we have that the extension of λ_i in V^* is consistent with:

$$w_1 \succ \dots \succ w_i \succ \dots \succ w_x \succ x \succ S_i \succ c \succ T_i,$$

implying again that $w_i \succ u_i$ in these votes. Therefore, we have:

$$D_{V^*}(w_i, u_i) = D_V(w_i, u_i) + k + (t - k) = -2t + t = -t.$$

We know that the maximin score of c is less than or equal to $-t$, since $D_{V^*}(c, l_1) = -t$, and we now have that the maximin score of w_i is $-t$. This overrules c as the unique winner in V^* , contradicting our assumption to that effect. This completes the proof. \square

3.3 Copeland Voting Rule

We now describe the reduction for POSSIBLE WINNER parameterized by the number of candidates, for the Copeland voting rule.

Theorem 4. *The POSSIBLE WINNER problem for the Copeland voting rule, when parameterized by the number of candidates, does not admit a polynomial kernel unless $\text{CoNP} \subseteq \text{NP/Poly}$.*

PROOF. Let $(\mathcal{U}, \mathcal{F}, k)$ be an instance of SMALL UNIVERSE SET COVER, where $\mathcal{U} = \{u_1, \dots, u_m\}$, and $\mathcal{F} = \{S_1, \dots, S_t\}$. For the purpose of this proof, we assume (without loss of generality) that $m \geq 6$. We now construct an instance (\mathcal{C}, V, c) of POSSIBLE WINNER as follows.

Candidates. $\mathcal{C} := \mathcal{U} \uplus \{z, c, d, w\}$.

Partial Votes, P . The first part of the voting profile comprises of m partial votes, and will be denoted by P . For each $1 \leq i \leq m$, we first consider a profile built on a total order:

$$\eta_i := \mathcal{U} \setminus S_i \succ z \succ c \succ d \succ S_i \succ w$$

Now, we obtain a partial order λ_i based on η_i as follows:

$$\lambda_i := \eta_i \setminus (\{z, c\} \times (S_i \uplus \{d, w\}))$$

The profile P consists of $\{\lambda_i \mid 1 \leq i \leq m\}$.

Complete Votes, Q . We now describe the remaining votes in the profile, which are linear orders designed to achieve specific pairwise difference scores among the candidates. This profile, denoted by Q , is defined according to lemma 2 to contain votes such that $D(c, d) = t - 2k + 1$, $D(z, w) = t - 2k - 1$, $D(c, u_i) = t - 1$, $D(c, z) = t + 1$, $D(c, w) = -t - 1$, $D(u_i, d) = D(z, u_i) = t + 1$, for all $1 \leq i \leq m$, $D(z, d) = t + 1$, $D(u_i, u_j) = t + 1$, for all $j \in [i + 1, i + \lfloor m/2 \rfloor]$, where addition is modulo m , are the pairwise score differences of $P \uplus Q$. We note that the for all $c, c' \in \mathcal{C}$, the difference $|D(c, c') - D_P(c, c')|$ is always even, as long t is odd and the number of sets in \mathcal{F} that contain an element $a \in \mathcal{U}$ is always odd. Note that the latter can always be ensured without loss of generality: indeed, if $a \in \mathcal{U}$ occurs in an even number of sets, then we can always add the set $\{a\}$ if it is missing and remove it if it is present, flipping the parity in the process. The number of sets t can be assumed to be odd by adding a dummy element and a dummy set that contains the said element.

Thus the constructed instance of POSSIBLE WINNER is (\mathcal{C}, V, c) , where $V := P \uplus Q$. We now turn to the proof of correctness.

In the forward direction, let $\mathcal{H} \subseteq \mathcal{F}$ be a set cover of size at most k . Without loss of generality, let $|\mathcal{H}| = k$ (since a smaller set cover can always be extended artificially) and let $\mathcal{H} = \{S_1, \dots, S_k\}$ (by renaming).

If $i \leq k$, let:

$$\lambda_i^* := \mathcal{U} \setminus S_i \succ z \succ c \succ d \succ S_i \succ w$$

If $i > k$, let:

$$\lambda_i^* := \mathcal{U} \setminus S_i \succ d \succ S_i \succ w \succ z \succ c$$

Clearly λ_i^* extends λ_i for all $i \in 1 \leq i \leq k$. Let V^* denote the extended profile consisting of the votes $\{\lambda_i^* \mid 1 \leq i \leq k\} \uplus Q$. We now claim that c is the unique winner with respect to the Copeland voting rule in V^* .

First, consider the candidate z . Between z and u_i , even if z loses to u_i in every λ_i^* , because $D(z, u_i) = t + 1$, z wins the pairwise election between z and u_i . The same argument holds between z and d . Therefore, the Copeland score of z , no matter how the partial votes were extended, is at least $(m + 1)$.

Further, note that all candidates (apart from c) have a Copeland score of less than $(m + 1)$, because they are guaranteed to lose to at least three candidates (assuming $m \geq 6$). In particular, observe that u_i loses to at least $\lfloor m/2 \rfloor$ candidates, and d loses to all u_i (merely by its position in the extended votes), and w loses to all u_i (because of way the scores were designed). Therefore, the Copeland score of all candidates in $\mathcal{C} \setminus \{z, c\}$ is strictly less than the Copeland score of z , and therefore they cannot be possible winners.

Now we restrict our attention to the contest between z and c . First note that c beats every u_i : since the sets of \mathcal{H} form a set cover, every u_i is present in some λ_i^* for $i \leq k$, in a position after c . Since the difference score between c and u_i was $(t - 1)$, even if c suffered defeat in every other extension, we have the pairwise score of c and u_i being at least $t - 1 - (t - 1) + 1 = 1$, which implies that c defeats every u_i in their pairwise election. Note that c also defeats d by getting ahead of d in k votes, making its final score $t - 2k + 1 + k - (t - k) = 1$. Finally, w defeats c , simply by the preset difference score. Hence, the Copeland score of c is $(m + 2)$.

Now, all that remains to be done is to rule z out of the running. Note that z is defeated by w in their pairwise election: this is because z defeats w in k of the extended votes, and is defeated by w in the remaining. This implies that its final pairwise score with respect to w is at most $t - 2k - 1 + k - (t - k) = -1$. Also note that z loses to c because of its predefined difference score. Thus, the Copeland score of z in the extended vote is exactly $(m + 1)$, and thus c is the unique winner of the extended vote.

We now turn to the reverse direction. Let P^* be an extension of P such that $V^* := P^* \uplus Q$ admits c as an unique winner with respect to the Copeland voting rule. As with the argument for maximin voting rule, we first argue that P^* must admit a certain structure, which will lead us to an almost self-evident set cover for \mathcal{U} .

Let us denote by P_C^* the set of votes in P^* which are consistent with $c \succ d$, and let P_W^* be the set of votes in P^* which are consistent with $w \succ z$. Note that the votes in P_C^* necessarily have the form:

$$\lambda_i^* := \mathcal{U} \setminus S_i \succ z \succ c \succ d \succ S_i \succ w$$

and those in P_W^* have the form:

$$\lambda_i^* := \mathcal{U} \setminus S_i \succ d \succ S_i \succ w \succ z \succ c$$

It is easy to check that this structure is directly imposed by the relative orderings that are fixed by the partial orders.

Before we argue the details of the scores, let us recall that in any extension of P , z loses to c and z wins over d and all candidates in \mathcal{U} . Thus the Copeland score of z is at least $(m + 1)$. On the

other hand, in any extension of P , c loses to w , and therefore the Copeland score of c is at most $(m + 2)$. (These facts follow from the analysis in the forward direction.)

Thus, we have the following situation. If z wins over w , then c cannot be the unique winner in the extended vote, because the score of z goes up to $(m + 2)$. Similarly, c cannot afford to lose to any of $\mathcal{U} \uplus \{d\}$, because that will cause its score to drop below $(m + 2)$, resulting in either a tie with z , or worse. These facts will successively lead us to the correctness of the reverse direction.

Now, let us return to the sets P_C^* and P_W^* . If P_C^* has more than k votes, then z wins over w : the final score of z is at least $t - 2k - 1 + (k + 1) - (t - k - 1) = 1$, and we have a contradiction. If P_C^* has fewer than k votes, then c loses to d , with a score of at most $t - 2k + 1 + (k - 1) - (t - k + 1) = -1$, and we have a contradiction.

Finally, suppose the sets corresponding to the votes of P_C^* do not cover \mathcal{U} . Consider an element u_i of \mathcal{U} not covered by the union of these sets. Observe that c now loses the pairwise election between itself and u_i and is no longer in the running for being the unique winner in the extended vote. Therefore, the sets corresponding to the votes of P_C^* form a set cover of size exactly k , as desired. \square

3.4 Bucklin Voting Rule

We now describe the reduction for POSSIBLE WINNER parameterized by the number of candidates, for the Bucklin voting rule.

Theorem 5. *The POSSIBLE WINNER problem for the Bucklin voting rule, when parameterized by the number of candidates, does not admit a polynomial kernel unless $\text{CoNP} \subseteq \text{NP/Poly}$.*

PROOF. Let $(\mathcal{U}, \mathcal{F}, k)$ be an instance of SMALL UNIVERSE SET COVER, where $\mathcal{U} = \{u_1, \dots, u_m\}$, and $\mathcal{F} = \{S_1, \dots, S_t\}$. Without loss of generality, we assume that $t > k + 1$, and that every set has at least two elements. We now construct an instance (\mathcal{C}, V, c) of POSSIBLE WINNER as follows.

Candidates. $\mathcal{C} := \mathcal{U} \uplus \{z, c, a\} \uplus W \uplus D_1 \uplus D_2 \uplus D_3$, where D_1 , D_2 , and D_3 are sets of “dummy candidates” such that $|D_1| = m$, $|D_2| = 2m$, and $|D_3| = m$. $W := \{w_1, w_2, \dots, w_{2m}\}$.

Partial Votes, P . The first part of the voting profile comprises of t partial votes, and will be denoted by P . For each $1 \leq i \leq t$, we first consider a profile built on a total order:

$$\eta_i := \mathcal{U} \setminus S_i \succ S_i \succ w_{i\%m} \succ w_{(i+1)\%m} \succ z \succ c \succ D_3 \succ \dots$$

Now, we obtain a partial order λ_i based on η_i as follows:

$$\lambda_i := \eta_i \setminus (\{w_{i\%m}, w_{(i+1)\%m}, z, c\} \uplus D_3) \times S_i$$

The profile P consists of $\{\lambda_i \mid 1 \leq i \leq t\}$.

Complete Votes, Q .

$$\begin{aligned} t - k - 1 & : D_1 \succ z \succ c \succ \dots \\ 1 & : D_1 \succ c \succ a \succ z \succ \dots \\ k - 1 & : D_2 \succ \dots \end{aligned}$$

We now show that $(\mathcal{U}, \mathcal{F}, k)$ is an YES instance if and only if (\mathcal{C}, V, c) is an YES instance. Suppose, $\{S_j : j \in J\}$ forms a set cover. Then, consider the following extension of P :

$$(\mathcal{U} \setminus S_j) \succ w_{j\%m} \succ w_{(j+1)\%m} \succ z \succ c \succ D_3 \succ S_j \dots, \text{ for } j \in J$$

$$(\mathcal{U} \setminus S_j) \succ S_j \succ w_{j\%m} \succ w_{(j+1)\%m} \succ z \succ c \succ D_3 \succ \dots, \text{ for } j \notin J$$

We claim that in this extension, c is the unique winner with Bucklin score $(m + 2)$. First, let us establish the score of c . The candidate c is within the top $(m + 1)$ choices in $(t - k)$ of the complete votes. In all the sets that form the set cover, c is ranked within the first $(m + 2)$ votes in the proposed extension of the corresponding vote

$j \in J$ forms a set cover. If not, then suppose an element v_i is not covered by $\{S_j : j \in J\}$. Then, the candidate v_i comes before c in all the extensions which makes $D(v_i, c)$ become $(t + 2)$, which in turn ties with $D(c, w)$. This again contradicts the fact that c is the unique winner. Therefore, if there is an extension that makes c the unique winner, then we have the desired set cover. \square

4. POLYNOMIAL KERNELS FOR COALITIONAL MANIPULATION

We now describe a kernelization algorithm for any scoring rule which has the following properties. For $m \in \mathbb{N}$, let $(\alpha_1, \dots, \alpha_m)$ and $(\alpha'_1, \dots, \alpha'_{m+1})$ be the normalized score vectors for a scoring rule for an election with m and $(m + 1)$ candidates respectively. Then $\alpha_1 = O(\text{poly}(m))$ and $\alpha_i = \alpha'_i$ for all $1 \leq i \leq m$. For ease of exposition, we present the result for the Borda voting rule only.

Theorem 7. *The COALITIONAL MANIPULATION problem for the Borda voting rule admits a polynomial kernel when the number of manipulators is $O(\text{poly}(m))$.*

PROOF. Let c be the candidate whom the manipulators aim to make winner. Let M be the set of manipulators and \mathcal{C} candidate set. Let $s_{NM}(x)$ be the score of candidate x from the votes of the non-manipulators. Without loss of generality, we assume that, all the manipulators place c at top position in their votes. Hence, the final score of c is $s_{NM}(c) + |M|(m - 1)$, which we denote by $s(c)$. Now, if $s_{NM}(x) \geq s(c)$ for any $x \neq c$, then c cannot win and we output *no*. Hence, we assume that $s_{NM}(x) < s(c)$ for all $x \neq c$. Now let us define $s_{NM}^*(x)$ as follows.

$$s_{NM}^*(x) := \max\{s_{NM}(x), s_{NM}(c)\}$$

Also define $s_{NM}^*(c)$ as follows.

$$s_{NM}^*(c) := s_{NM}(c) - |M|$$

We define a COALITIONAL MANIPULATION instance with $(m + 1)$ candidates as (\mathcal{C}', NM, M, c) , where $\mathcal{C}' = \mathcal{C} \uplus \{d\}$ is the candidate set, M is the set of manipulators, c is the distinguished candidate, and NM is the non-manipulators' vote is such that it generates score of $x \in \mathcal{C}$ to be $K + (s_{NM}^*(x) - s_{NM}(c))$, where $K \in \mathbb{N}$ is same for $x \in \mathcal{C}$, and the score of d is less than $K - m|M|$. The existence of such a voting profile NM of size $\text{poly}(m)$ is due to Lemma 1. Hence, once we show the equivalence of these two instances, we have a kernel whose size is polynomial in m . The equivalence of the two instances follows from the facts that (1) the new instance has $(m + 1)$ candidates and c is always placed at the top position without loss of generality, c gets $|M|$ score more than the initial instance and this is compensated in $s_{NM}^*(c)$, (2) the relative score difference from the final score of c to the current score of every $x \in \mathcal{C} \setminus \{c\}$ is same in both the instances, and (3) in the new instance, we can assume without loss of generality that the candidate d will be placed in the second position in all the manipulators' votes. \square

We now move on to the voting rules that are based on the weighted majority graph. The reduction rules modify the weighted majority graph maintaining the property that there exists a set of votes that can realize the modified weighted majority graph. In particular, the final weighted majority graph is realizable with a set of votes.

Theorem 8. *The COALITIONAL MANIPULATION problem for the maximin voting rule admits a polynomial kernel when the number of manipulators is $O(\text{poly}(m))$.*

PROOF. Let c be the distinguished candidate of the manipulators. Let M be the set of manipulators. We can assume that $|M| \geq 2$ since for $|M| = 1$, the problem is in P [1]. Define s to be $\min_{x \in \mathcal{C} \setminus \{c\}} D_{(\mathcal{V} \setminus M)}(c, x)$. So, s is the maximin score of the candidate c from the votes except from M . Since, the maximin voting rule is monotone, we can assume that the voters in M put the candidate c at top position of their preferences. Hence, c 's final maximin score will be $s + |M|$. This provides the following reduction rule.

Reduction rule 1. *If $s + |M| \geq 0$, then output Yes.*

In the following, we will assume $s + |M|$ is negative. Now we propose the following reduction rules on the weighted majority graph.

Reduction rule 2. *If $D_{(\mathcal{V} \setminus M)}(c_i, c_j) < 0$ and $D_{(\mathcal{V} \setminus M)}(c_i, c_j) > 2|M| + s$, then make $D_{(\mathcal{V} \setminus M)}(c_i, c_j)$ either $2|M| + s + 1$ or $2|M| + s + 2$ whichever keeps the parity of $D_{(\mathcal{V} \setminus M)}(c_i, c_j)$ unchanged.*

If $D_{(\mathcal{V} \setminus M)}(c_i, c_j) > 2|M| + s$, then $D_{\mathcal{V}}(c_i, c_j) > |M| + s$ irrespective of the way the manipulators vote. Hence, whether or not the maximin score of c_i and c_j will exceed the maximin score of c does not get affected by this reduction rule. Hence, reduction rule 2 is sound.

Reduction rule 3. *If $D_{(\mathcal{V} \setminus M)}(c_i, c_j) < s$, then make $D_{(\mathcal{V} \setminus M)}(c_i, c_j)$ either $s - 1$ or $s - 2$ whichever keeps the parity of $D_{(\mathcal{V} \setminus M)}(c_i, c_j)$ unchanged.*

The argument for the correctness of reduction rule 3 is similar to the argument for reduction rule 2. Here onward, we may assume that whenever $D_{(\mathcal{V} \setminus M)}(c_i, c_j) < 0$, $s - 2 \leq D_{(\mathcal{V} \setminus M)}(c_i, c_j) \leq 2|M| + s + 2$

Reduction rule 4. *If $s < -4|M|$ then subtract $s + 5|M|$ whenever $s - 2 \leq D_{(\mathcal{V} \setminus M)}(c_i, c_j) \leq 2|M| + s + 2$.*

The correctness of reduction rule 4 follows from the fact that it adds linear fixed offsets to all the edges of the weighted majority graph. Hence, if there a voting profile of the voters in M that makes the candidate c win in the original instance, the same voting profile will make c win the election in the reduced instance and vice versa. Now, we have a weighted majority graph with $O(|M|)$ weights for every edge. Also, all the weights have uniform parity and thus the result follows from lemma 2. \square

The proof of the following theorem is analogous to the proof of Theorem 8. In the interest of space, we omit the proof.

Theorem 9. *The COALITIONAL MANIPULATION problem for the Copeland and ranked pairs voting rules admit a polynomial kernel when the number of manipulators is $O(\text{poly}(m))$.*

5. CONCLUSION AND FUTURE WORK

Here, we showed that the POSSIBLE WINNER problem does not admit a polynomial kernel for many common voting rules under the complexity theoretic assumption that $\text{CoNP} \subseteq \text{NP/Poly}$ is not true. We also showed the existence of polynomial kernels for the COALITIONAL MANIPULATION problem for many common voting rules. This shows that the POSSIBLE WINNER problem is a significantly harder problem than the COALITIONAL MANIPULATION problem, although both the problems are in NPC.

There are other interesting parameterizations of these problems for which fixed parameter tractable algorithms are known but the corresponding kernelization questions are still open. One such parameter is the total number of pairs s in all the votes for which an ordering has not been specified. With this parameter, a simple $O(2^s \cdot \text{poly}(m, n))$ algorithm is known [8]. However, the corresponding kernelization question is still open.

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