

# On the Maximization of Influence Over an Unknown Social Network

Extended Abstract

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## ABSTRACT

Influence maximization is a well-investigated problem which asks for key individuals who have significant influence in a given social network. This paper addresses this problem when the social network structure is hidden. We adopt the framework of influence learning from samples and build a neural network model to represent the information diffusion process. Based on the model, we propose two new algorithms NeuGreedy and NeuMax. NeuGreedy simulates the traditional greedy algorithm whilst NeuMax utilizes the weights of connections between neurons. We test the algorithms on both synthetic and real-world datasets. The results verify the effectiveness of the proposed methods as compared to existing algorithms with or without the network structure.

## KEYWORDS

Social network; social influence; influence maximization; neural network; hidden network structure; machine learning

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## 1 INTRODUCTION

Influence maximization (IM) is a crucial problem to many fields from viral marketing to crowd mobilization [3, 16]. The problem asks for a small set  $S$  of *seed nodes* in a given social network who would spread messages among adjacent nodes in the hope to trigger a cascade of information propagation. The number of nodes eventually affected by this propagation process represents the influence  $f(S)$  of the seed nodes  $S$ . The problem aims to find the seed nodes that have maximum influence [6, 17]. The problem apparently relies on the network structure which describes links between nodes [4, 13, 14, 20, 21]. In the real-world, however, this network structure is often

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unavailable due to, e.g., difficulty in collecting accurate social link data or privacy concerns. It is thus important to investigate the problem without the presence of the network structure.

Several studies address IM without a given network structure. Some works, e.g., [5, 12, 18, 19] assume that the network can be queried, while others, e.g., [7, 8, 15, 22] assume the presence of *cascade information* which makes the influence function PAC learnable. Instead, we adopt the paradigm of *influence maximization from samples* (IMFS), which aims to optimize the influence function  $f$  given sample pairs of the form  $(S, f(S))$ . Assuming the samples are taken from a specific distribution, the OPS algorithm solves IMFS and achieves an optimization rate of  $\tilde{O}(n^{-1/4})$  with polynomially many samples [2]. [1] then proposed the COPS algorithm for networks with a clear community structure [11]. The algorithm outperforms OPS for samples generated by the independent cascade (IC) model. A number of limitations exist with these methods as: Firstly, these methods require certain specific sample distributions; Then, OPS fails to capture other information diffusion models such as the linear threshold (LT) model.

This paper addresses IMFS with a learning-centered approach. (1) We use a neural network framework that trains a *influence prediction model* (IPM) to represent influence. (2) Two algorithms are proposed based on IPM: NeuGreedy which simulates the original greedy algorithm as presented in [10]; and NeuMax which utilizes the neural network structure. These algorithm exhibit superior performance as compared to the benchmark algorithms.

## 2 PROBLEM FORMULATION

Let  $V$  be a set of nodes denoting a set of  $n$  agents. A *diffusion instance* on  $V$  captures the initialization and outcome of an information diffusion process, i.e., it is a pair  $(S, R)$  where  $S \subseteq R \subseteq V$ ;  $S$  is called the *seed set* and  $R$  is called the *activated set*. A *diffusion mechanism*  $\mathcal{M}$  is a probabilistic distribution over all diffusion instances on  $V$ .

The *influence function*  $f: 2^V \rightarrow [0, 1]^V$  that corresponds to  $\mathcal{M}$  is defined by  $f(S) = (f(S)_v)_{v \in V}$  where  $f(S)_v$  is the probability that  $v$  becomes activated in a diffusion instance in  $\mathcal{M}$  with seed set  $S$ . Set  $|f(S)| := \sum_{v \in V} f(S)_v$ ; it expresses the social influence of the set  $S$ . *Influence maximization from samples* (IMFS) assumes that we are given samples from the diffusion mechanism  $\mathcal{M}$  and  $k \in \mathbb{N}$ . The goal is to find a set  $S \subseteq V$  with  $|S| \leq k$  and the maximum  $|f(S)|$ .

### 3 METHODS

We train a feed-forward neural network to represent the influence function  $f$  given a collection  $H$  of diffusion instances. The problem can be seen as multi-label classification: A sample  $(S, R)$  is multi-hop encoded as a pair of  $\{0, 1\}$ -vectors  $\vec{S}$  and  $\vec{R}$  where for any set  $U \subseteq V$ , the entry  $\vec{U}_v = 1$  if  $v \in U$  and  $\vec{U}_v = 0$  otherwise. We use an  $m$ -dimensional bias vector  $\vec{b} = (b_1, \dots, b_m)$ . Let  $\varphi_{>0}: \mathbb{R}^m \rightarrow \mathbb{R}^m$  be the transformation that turns the negative entries of any vector into 0. Let  $\sigma$  denote the sigmoid squash function on a vector. Given matrices  $\vec{K}, \vec{L}, \vec{b}$ , the influence prediction model (IPM) is a vector  $\hat{f}_{\vec{K}, \vec{L}, \vec{b}}(S)$  for any set  $S \subseteq V$  by  $\hat{f}_{\vec{K}, \vec{L}, \vec{b}}(S) = \sigma(\varphi_{>0}(\vec{S}(\vec{K} + \vec{b}))\vec{L}^T)$ . Using gradient descent, we find the parameters  $\vec{K}, \vec{L}$  and  $\vec{b}$  that minimize the cross-entropy loss  $\mathcal{L}(f, \hat{f}_{\vec{K}, \vec{L}, \vec{b}}) = \sum_{v \in V} f(S)_v \log(\hat{f}_{\vec{K}, \vec{L}, \vec{b}}(S)_v)$ .

**The NeuGreedy algorithm.** The greedy algorithm exploits submodularity of the influence function and solves the IM problem with a given social network structure with a guaranteed approximation ratio of  $1 - 1/e$  [10]. The procedure builds the seed set  $S$  by iteratively adding to  $S$  the agent with the highest marginal reward, i.e., the net increase in  $S'$  influence. The NeuGreedy algorithm takes the same idea using the optimized IPM as a surrogate of the diffusion mechanism  $\mathcal{M}$  to evaluate the influence function.

**The NeuMax algorithm.** Recall that the matrix  $\vec{K}$  encodes the interplay between a set  $S \subseteq V$  and  $m$  features, while  $\vec{L}$  encodes the interplay between the same  $m$  features and the activated node set  $R \subseteq V$ . The “strength” of a node  $v \in S$  to the  $i$ th feature is expressed by the  $i$ th row vector in  $\vec{K}$ , while the “strength” of the  $i$ th feature to a node  $u \in R$  is expressed by the  $i$ th row vector in  $\vec{L}$ . Define the influence matrix as the product  $\vec{W} = \vec{K}\vec{L}^T$ . The  $(i, j)$ -th entry in  $\vec{W}$  represents in a certain sense how much activating node  $i$  may lead to the activation of node  $j$ . The core idea behind the NeuMax algorithm is to extract influential nodes by analyzing the influence matrix  $\vec{W}$ . Set  $\text{importance}(v) := \sum_{u \in V} \vec{W}(v, u)$ . For  $i \in V$ , normalize the column vector  $\vec{W}(i)$  so that the lowest value having value 0 and the highest having value 1 to get  $\tilde{W}(i)$ .  $\tilde{W}$  denotes the normalized influence matrix  $[\tilde{W}(1) \dots \tilde{W}(n)]$ . For a seed set  $S$  and a threshold  $\theta \in [0, 1]$ , define the expansion as

$$\text{Expand}_\theta(S) = \left\{ v \in V \mid \sum_{u \in S} \tilde{W}(u, v) > \theta \right\}.$$

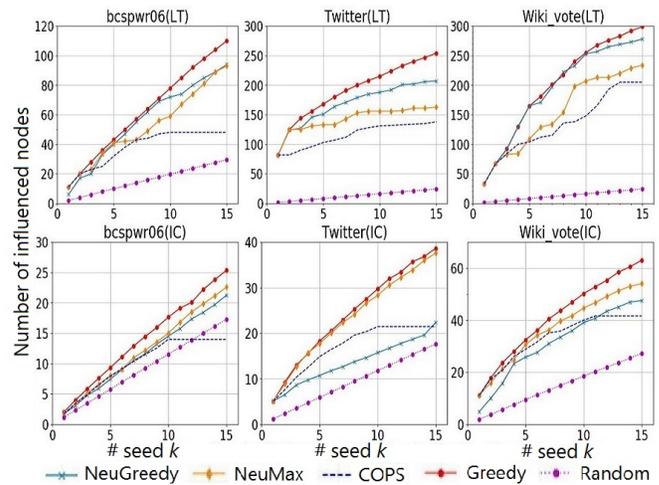
The expanded set of  $S$  approximates the influence function  $f$ . To build a seed set, the NeuMax algorithm greedily selects nodes utilizing both views above. At every iteration, it evaluates the expansion  $A$  of the current seeds  $S$ . If  $|A| < n$ , it selects a node by the column view. Otherwise, it applies the row view.

### 4 EXPERIMENTS

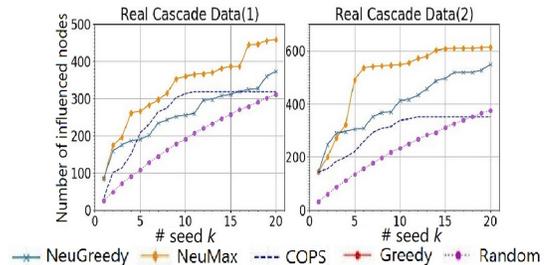
Our experiments use three benchmark algorithms: **•Random.** Here the  $k$  seeds are selected at random. **•COPS.** [1] COPS is shown to have significantly better performance than other IMFS algorithms. **•Greedy.** [9] The algorithm has guaranteed approximation ratio but relies on the given network structure. We verify our methods over generated datasets from three real-world network data sets: A

Twitter social network (soc-twitter-copen, 761 nodes, 1029 edges)<sup>1</sup>, a power network (bcspwr06, 899 nodes, 2914 edges)<sup>2</sup>, and an online voting network (rt-wiki-vote, 1454 nodes, 3377 edges<sup>2</sup>). To generate diffusion instances, we use LT and IC diffusion models. The generated instances are then used as training samples to produce our IPM. We also use the real-world diffusion instance dataset in [7] which contains 300 million blog posts and articles from 5,000 media sites. The data set contains 1000 agents and 29265 samples.

As shown in Fig. 1 (for real networks) and Fig. 2 (for the real-world samples), our algorithms clearly outperform the random benchmark by a large margin. They outperform COPS in most of the cases, and achieve comparable results as the greedy algorithm. For IC, NeuMax generally outperforms NeuGreedy while NeuGreedy is slightly better for LT. Over the real-world cascade data sets, NeuMax clearly outperforms the other algorithms, while COPS is much worse, matched even by the greedy benchmark with the number of seeds exceeds 20.



**Figure 1: Comparison across the datasets: bcspwr06 (left), twitter (mid) and wikivote (right). Samples are generated using LT (above) and IC (below) models.**



**Figure 2: Results on real-world samples. The greedy algorithm cannot be applied due to lack of network data.**

<sup>1</sup><http://konect.uni-koblenz.de/networks>

<sup>2</sup><http://networkrepository.com>

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