When Is It Acceptable to Break the Rules? Knowledge Representation of Moral Judgements Based on Empirical Data (Extended Abstract)

JAAMAS Track

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ABSTRACT

This paper explores how humans make contextual moral judgments to inform the development of AI systems capable of balancing rulefollowing with flexibility. We investigate the limitations of rigid constraints in AI, which can hinder morally acceptable actions in specific contexts, unlike humans who can override rules when appropriate. We propose a preference-based graphical model inspired by dual-process theories of moral judgment and conduct a study on human decisions about breaking the social norm of "no cutting in line." Our model outperforms standard machine learning methods in predicting human judgments and offers a generalizable framework for modeling moral decision-making across various contexts. This short paper summarizes the main findings of our paper published in the journal *Autonomous Agents and Multi-Agent Systems*. [2]

KEYWORDS

Moral decision-making, thinking fast and slow, human judgment

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1 INTRODUCTION

The increasing use of AI systems in real-world applications has raised significant concerns about their ethical alignment and behavior [10, 14, 16]. A key challenge is ensuring that AI systems operate within morally acceptable boundaries while avoiding issues like "specification gaming," where the system exploits loopholes in its design [1, 12, 15]. Traditional approaches to controlling AI behavior often rely on rigid, rule-based constraints. However, these can be either too restrictive—blocking reasonable actions—or too permissive, allowing harmful outcomes. In contrast, humans navigate such dilemmas with remarkable flexibility, intuitively overriding rules when context demands it. This human capacity for contextsensitive moral reasoning highlights the limitations of both static rule-based and reward specification approaches in AI [1, 5, 8].

To address this gap, we propose Scenario-Evaluation-Preference Networks (SEP-nets), an extension of CP-nets that allows for the representation of preferences not only over outcomes but also over decision contexts. Inspired by dual-process theories of moral cognition, SEP-nets model the two modes of human reasoning: fast, rule-based judgments (System 1) and slower, deliberative reasoning (System 2) [6, 7, 9, 17]. To validate our framework, we both collect data on and examine human moral judgments in the context of a simple yet illustrative social rule: "no cutting in line." This scenario reveals how people flexibly apply and override the rule based on contextual factors. By modeling these judgments using SEP-nets, we demonstrate improved prediction of human decisions compared to standard machine learning methods. Our work provides a promising foundation for building AI systems that can balance strict rule-following with the flexibility needed to navigate complex, real-world ethical dilemmas.

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Model	Accuracy	F1	Precision	Recall	Time (ms)
RandomForest	0.7651 (0.0069)	0.7119 (0.0190)	0.7402 (0.0121)	0.6859 (0.0276)	303 (24)
XGBoost	0.7870 (0.0227)	0.7307 (0.0417)	0.7822 (0.0325)	0.6868 (0.0556)	109 (4)
Vorace	0.7166 (0.0091)	0.6620 (0.0178)	0.6692 (0.0212)	0.6550 (0.0152)	181955 (10173)
SVM	0.7115 (0.0192)	0.6493 (0.0203)	0.6704 (0.0103)	0.6298 (0.0299)	6157 (454)
SEP-Table	0.7870 (0.0261)	0.7329 (0.0367)	0.7817 (0.0354)	0.6906 (0.0438)	22 (1)
SEP-SVM	0.7834 (0.0248)	0.7224 (0.0340)	0.7926 (0.0458)	0.6654 (0.0424)	259 (17)

Table 1: Average performance on the test sets and the average training time of the different models in a 5-fold cross-validation, standard deviation in parentheses. Best performance in bold.

2 SEP-NETS: SCENARIOS, EVALUATION, AND PREFERENCE NETWORKS

SEP-nets (Scenarios, Evaluation, and Preference Networks) are a generalization of CP-nets designed to model context-aware decisionmaking and human-like moral reasoning [13]. Unlike CP-nets [4], which only handle preference variables, SEP-nets introduce three distinct types of variables: *Scenario Variables (SVs)* that define the context of the decision, *Evaluation Variables (EVs)* that model cognitive processes of evaluation, and *Preference Variables (PVs)* that capture the final preferences. This allows SEP-nets to represent a richer and more flexible decision-making process. The variable dependencies follow a three-level acyclic structure, where SVs have no parents, EVs depend on SVs or other EVs, and PVs can depend on any other variable. This layered structure models both fast, intuitive decisions (System 1) and slower, deliberative reasoning (System 2), inspired by dual-process theories of moral cognition [3, 11].

The semantics of SEP-nets define a preference order over *SEP*outcomes, which are full assignments to all variables (SVs, EVs, and PVs). Two SEP-outcomes are comparable only if they share the same assignments for SVs and EVs. Preferences are then induced by a CP-net structure over the PVs. The process of identifying optimal outcomes follows three steps: (1) selecting a scenario by fixing the SVs, (2) setting the EVs according to evaluation functions that provide real-valued judgments, and (3) determining the most preferred assignment to the PVs according to the induced CPnet. This approach allows SEP-nets to model context-sensitive and ethically nuanced decision-making. When SVs and EVs are absent, SEP-nets reduce to classic CP-nets, demonstrating that SEP-nets are a strict extension of CP-nets. This richer formalism makes SEP-nets well-suited for modeling moral reasoning and context-dependent decision-making in AI systems.

3 DATA COLLECTION AND RESULTS

To test our model, we ran an experiment on Amazon MTurk. Informed consent was given by all participants and this study was approved by the Massachusetts Institute of Technology Institutional Review Board. Subjects were randomly assigned to one of three story contexts, in which subjects were asked to imagine that they were standing in line as a *deli* (12 scenarios), for a single-occupancy *bathroom* (7 scenarios), or at an *airport* security screening (6 scenarios). These contexts present the opportunity for someone to want to cut in line for a diverse range of reasons. We developed cases that manipulated (1) the amount of time by which the person cutting would delay the line, (2) the benefit that the person cutting would accrue by cutting, (3) the benefit that the people waiting would accrue by this person cutting, (4) the likelihood this particular scenario would happen at all.

To demonstrate its feasibility, two SEP-net variants were developed — SEP-SVM and SEP-Table — and tested on a binary prediction task. The goal was to model social behavior in a specific scenario, predicting whether an individual would allow another to cut in line based on contextual information (location and reason) and evaluations of welfare-related variables. The two SEP-nets differ in how evaluation is modeled: SEP-SVM employs Support Vector Machines (SVMs) to predict evaluation values, while SEP-Table uses empirical distributions derived from training data, partitioning evaluation values into quartiles. Both SEP-nets adopt a simple approach to construct the conditional preference table for the preference variable, using the most frequent preference in the training set.

To assess the performance of SEP-nets, they were compared with several machine learning models commonly used for binary classification, including XGBoost, Random Forest, VORACE (ensemble of neural networks), and a single SVM. All models were trained using 5-fold cross-validation, and their performance was evaluated using accuracy, precision, recall, F1-score, and training time. Table 1 reports the results that revealed that SEP-Table achieved the best overall performance, matching the state-of-the-art XGBoost in accuracy, while significantly outperforming it in training time. The SEP-SVM also achieved competitive performance, surpassing the single SVM and demonstrating the advantage of specialization within the SEP-net framework. The low variance observed in SEPnet results suggests their robustness and reliability in modeling context-dependent social decisions. This highlights the potential of SEP-nets to model complex human moral reasoning, capturing both intuitive (System 1) and deliberative (System 2) cognitive processes.

4 DISCUSSION

Our data collection and analysis highlight two central results. First, they provide evidence for our hypothesis about moral psychology, namely, that System 2 (outcome-based and agreement-based) reasoning is at play for our participants when deciding when to override rules. Second, they demonstrate that our novel formalism (SEP-nets) describes this process in a way that could be useful for enabling AI systems to understand the bounds of constraints. Additional results, details, and discussions can be found in the full version of our paper [2].

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